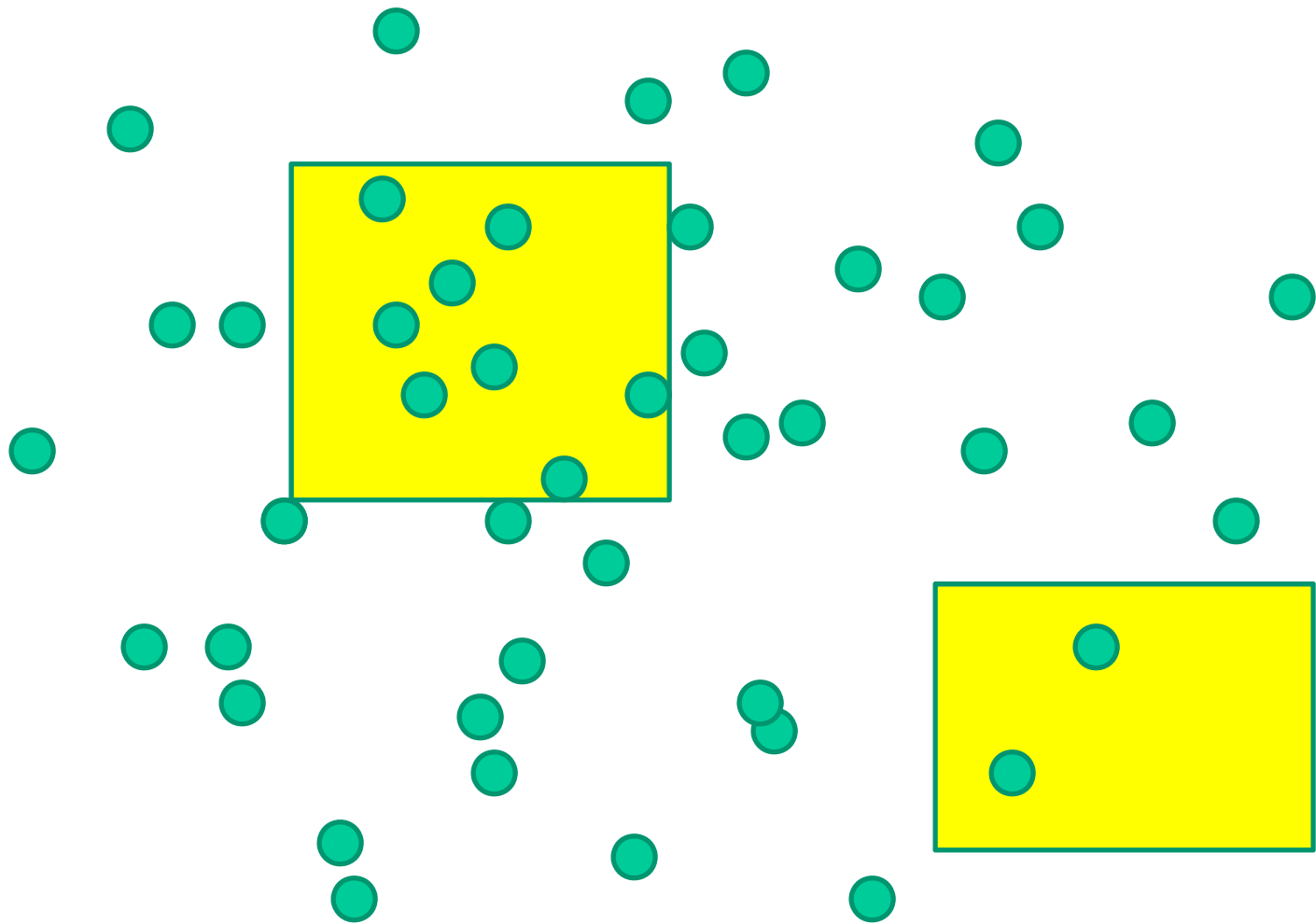


# Range searching

- Given a family  $F$  of regions and a set  $S$  of  $n$  points in the  $d$ -dimensional space, construct a data structure  $D(S)$ , such that we can do the following query efficiently.
- Reporting range query: Given any region  $R$  in  $F$ , report the set of points of  $S$  in  $R$ .
- Counting range query: answer the number of points of  $S$  in  $R$

# Rectangular range searching( $d=2$ )

- Given a set  $S$  of  $n$  points in the plane, construct a data structure  $D(S)$ , such that we can do the following query efficiently.
- Rectangle range query (counting): Given an axis parallel rectangle  $R$ , report the set of points of  $S$  in  $R$ .
- Answer the number of points of  $S$  in  $R$  efficiently

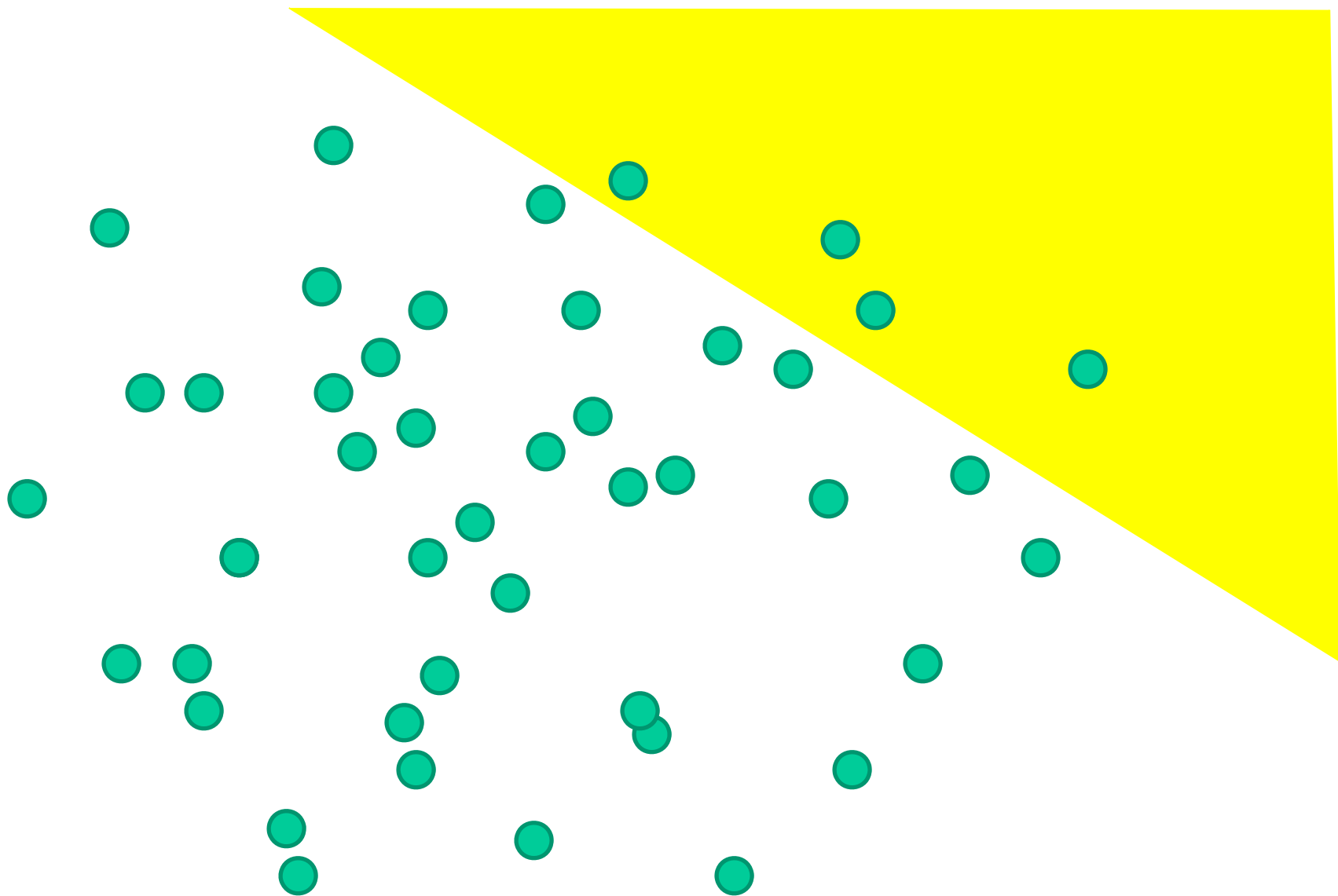


# Example of application

- Given a database of customers with (income, sales), report the set of customers such that
  - $2M < \text{income} < 2.5M$
  - $100K < \text{sales} < 300K$

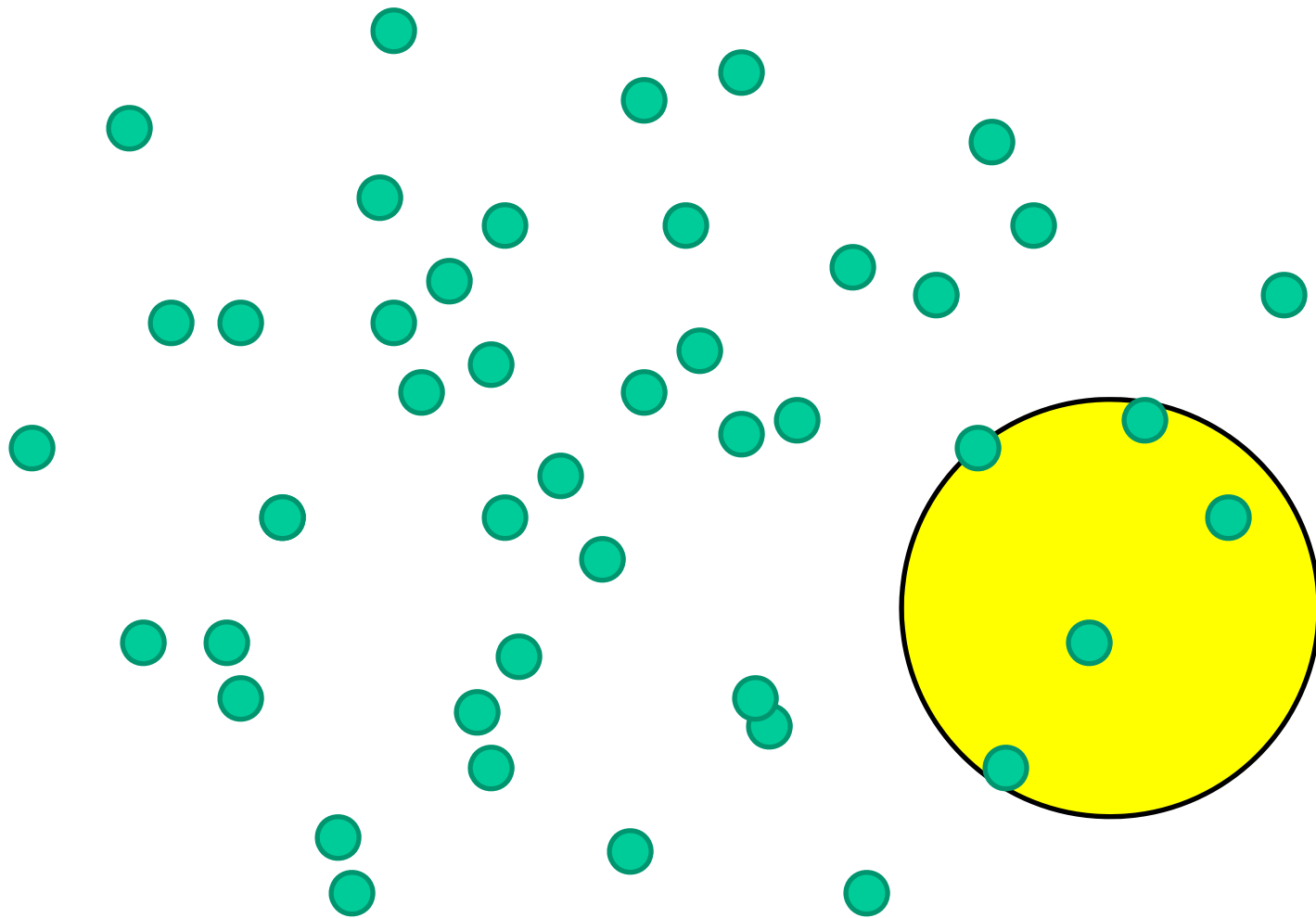
# Halfplane range searching( $d=2$ )

- Given a set  $S$  of  $n$  points in the plane, construct a data structure  $D(S)$ , such that we can do the following query efficiently.
- Halfplane range query: Given a halfplane  $H$ , report the set of points of  $S$  in  $H$  efficiently
- Answer the number of points of  $S$  in  $H$ .



# Circle range searching( $d=2$ )

- Given a set  $S$  of  $n$  points in the plane, construct a data structure  $D(S)$ , such that we can do the following query efficiently.
- Circle range query: Given a circle  $C$ , report the set of points of  $S$  inside  $C$ .
- Answer the number of points of  $S$  in  $C$ .



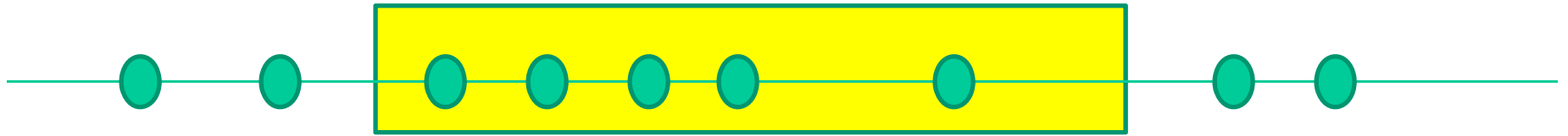


# Example

- Answer the set of Italian restaurants within distance of 300 M from Sendai station.

# Interval Range searching ( $d=1$ )

- Given a set  $S$  of  $n$  data with real key values, construct a data structure  $D(S)$ , such that we can do the following query efficiently.
- Interval range query (reporting): Given an interval  $I$ , report the set of data of  $S$  such that the key values are in  $I$ .
- Interval range query (counting): Answer the set of data of  $S$  whose key values are in  $I$ .



## Theorem 1

There is an  $O(n)$  size data structure  $D(S)$  to answer the reporting interval range query in  $O(k + \log n)$  time, where  $k$  is the number of reported elements. Also, the counting interval query can be computed in  $O(\log n)$  time using  $O(n)$  size data structure.

# Interval Range searching ( $d=1$ )

- Given a set  $S$  of  $n$  data with real key values  $\text{key}(x)$  and real data value  $\text{data}(x)$  for each  $x$  of  $S$ , construct a data structure  $D(S)$ , such that we can do the following query efficiently.
- Range minimum query : Given an interval  $I$ , report  $x$  of  $S$  such that the  $\text{key}(x)$  values are in  $I$  and minimizing  $\text{data}(x)$ .
  - Very important in data compression and data mining.

# Interval tree

- Store  $n$  data into a binary tree  $T(S)$
- The root of the tree contains  $S$
- The left child is  $T(S_1)$ , where  $S_1$  is the set of the  $n/2$  data with small key values
- The right child is  $T(S_2)$ , where  $S_2 = S - S_1$

A set stored at a vertex of the interval tree is called a primary set.

1,3,5,6,8,10,13,14

1,3,5,6

8,10,13,14

1,3

5,6

8,10

13,14

1

3

5

6

8

10

13

14

# Interval query using $T(S)$

- Lemma 1.

For any interval  $I$ ,  $S \cap I$  is represented as a union of  $O(\log n)$  primary sets.

- Lemma 2.

The primary sets considered in Theorem 1 can be computed in  $O(\log n)$  time.

- Theorem 2. The range minimum query can be computed in  $O(\log n)$  time

# Rectangular range searching( $d=2$ )

- Given a set  $S$  of  $n$  points in the plane, construct a data structure  $D(S)$ , such that we can do the following query efficiently.
- Rectangle range query (counting): Given an axis parallel rectangle  $R$ , report the set of points of  $S$  in  $R$ .
- Answer the number of points of  $S$  in  $R$  efficiently



# Rectangular range searching

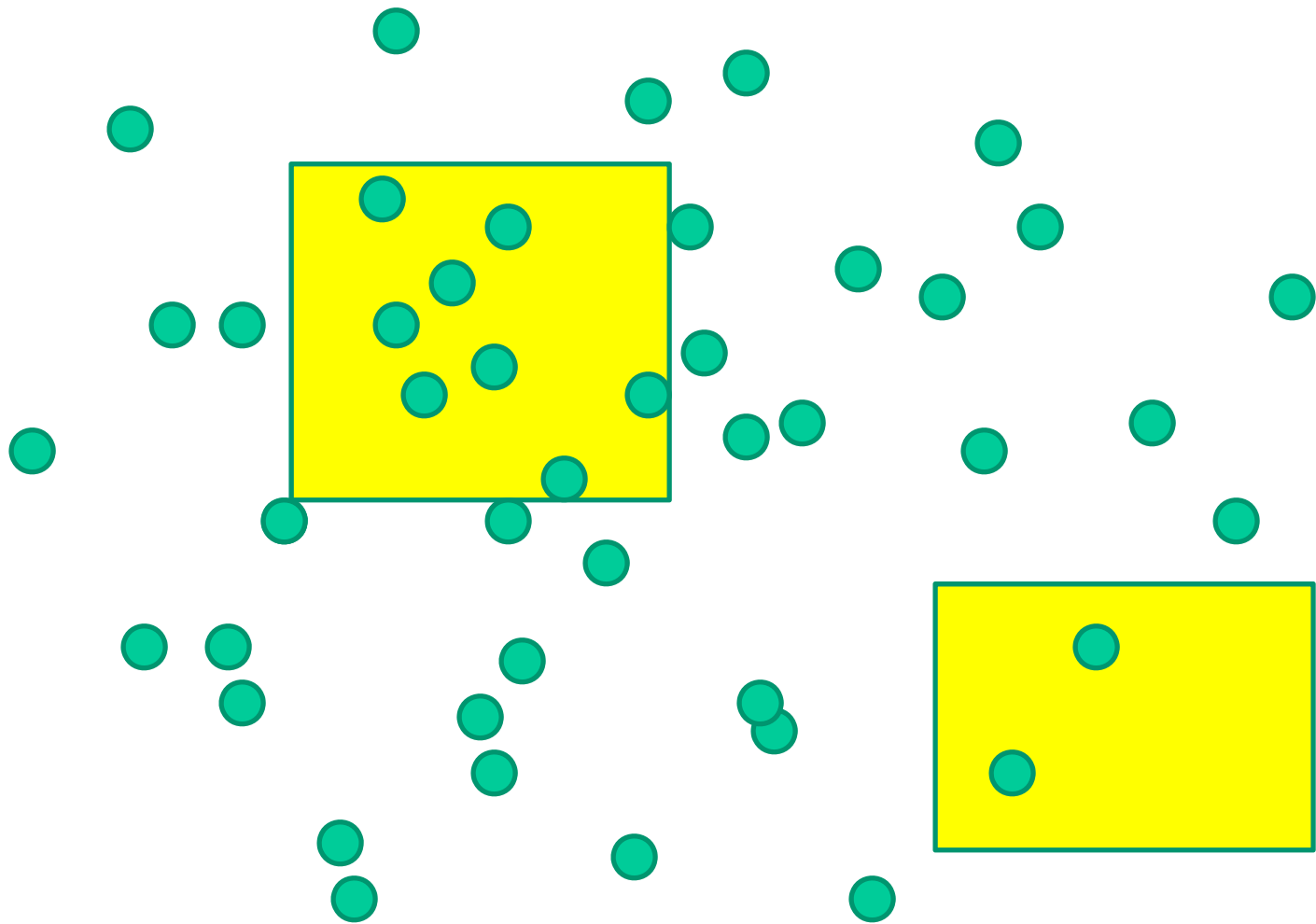
- Theorem 3

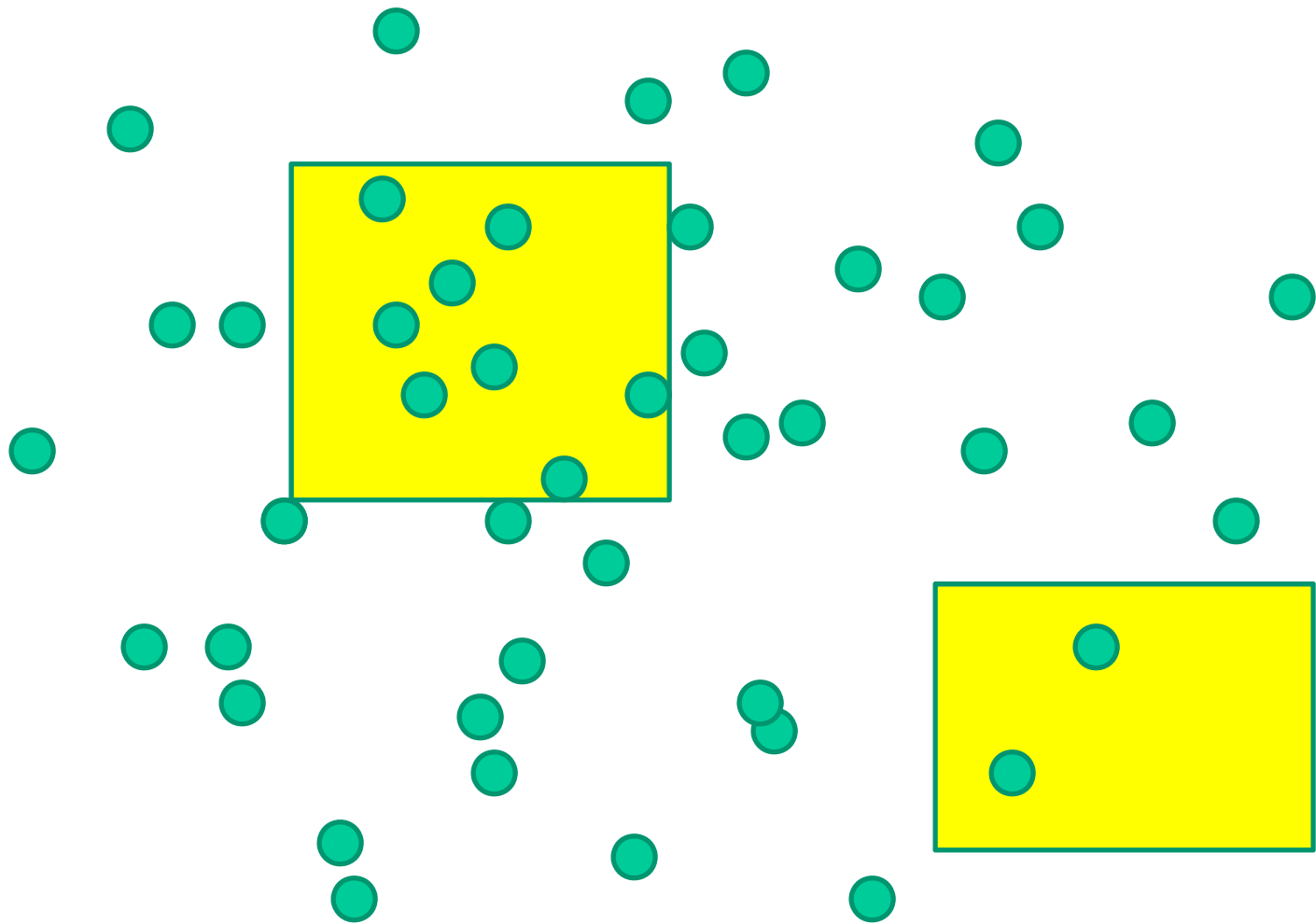
There is a data structure of size  $O(n \log n)$  to answer the reporting range query in  $O(k + \log n)$  time, where  $k$  is the number of reported elements.

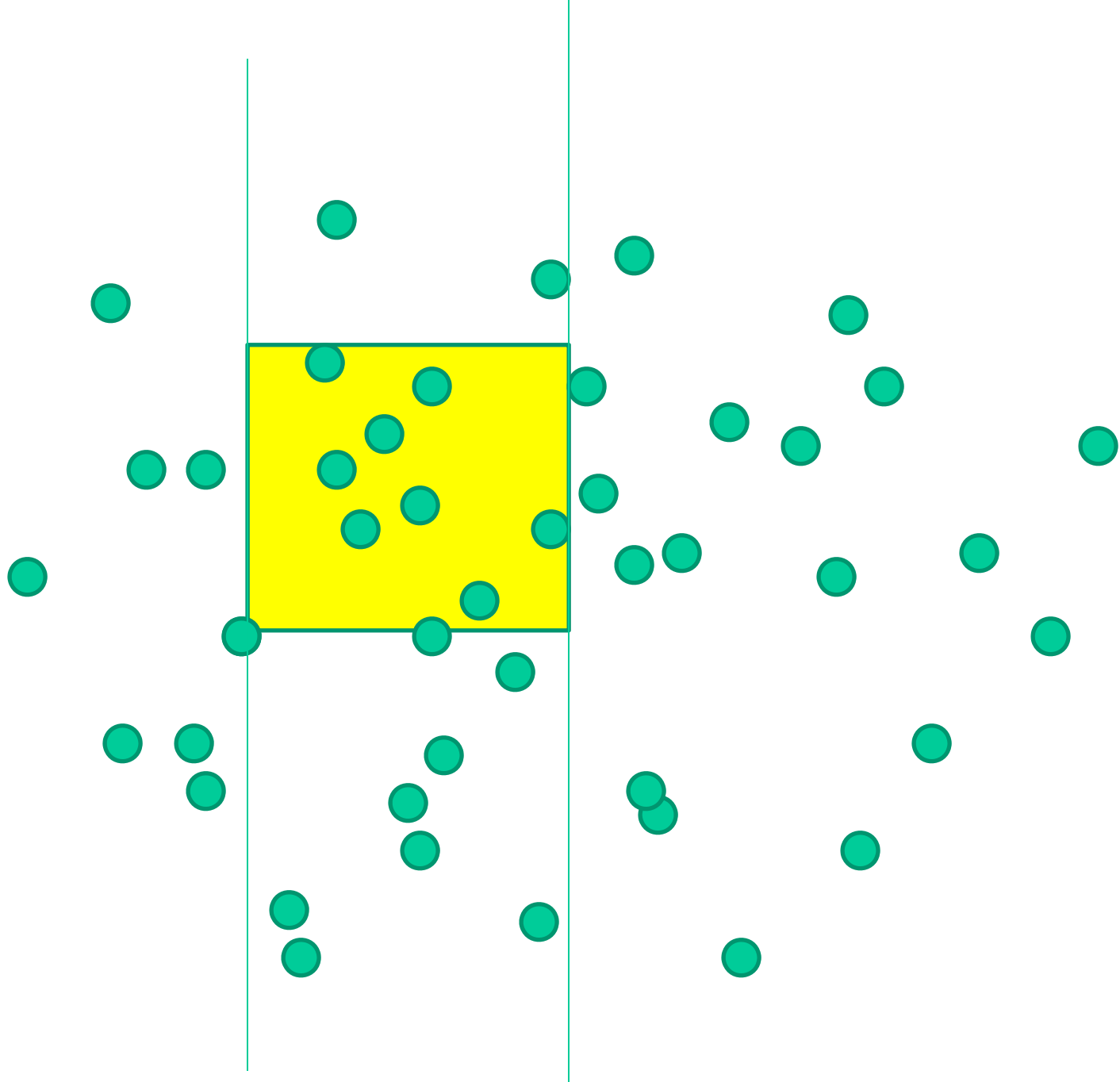
- Theorem 4.

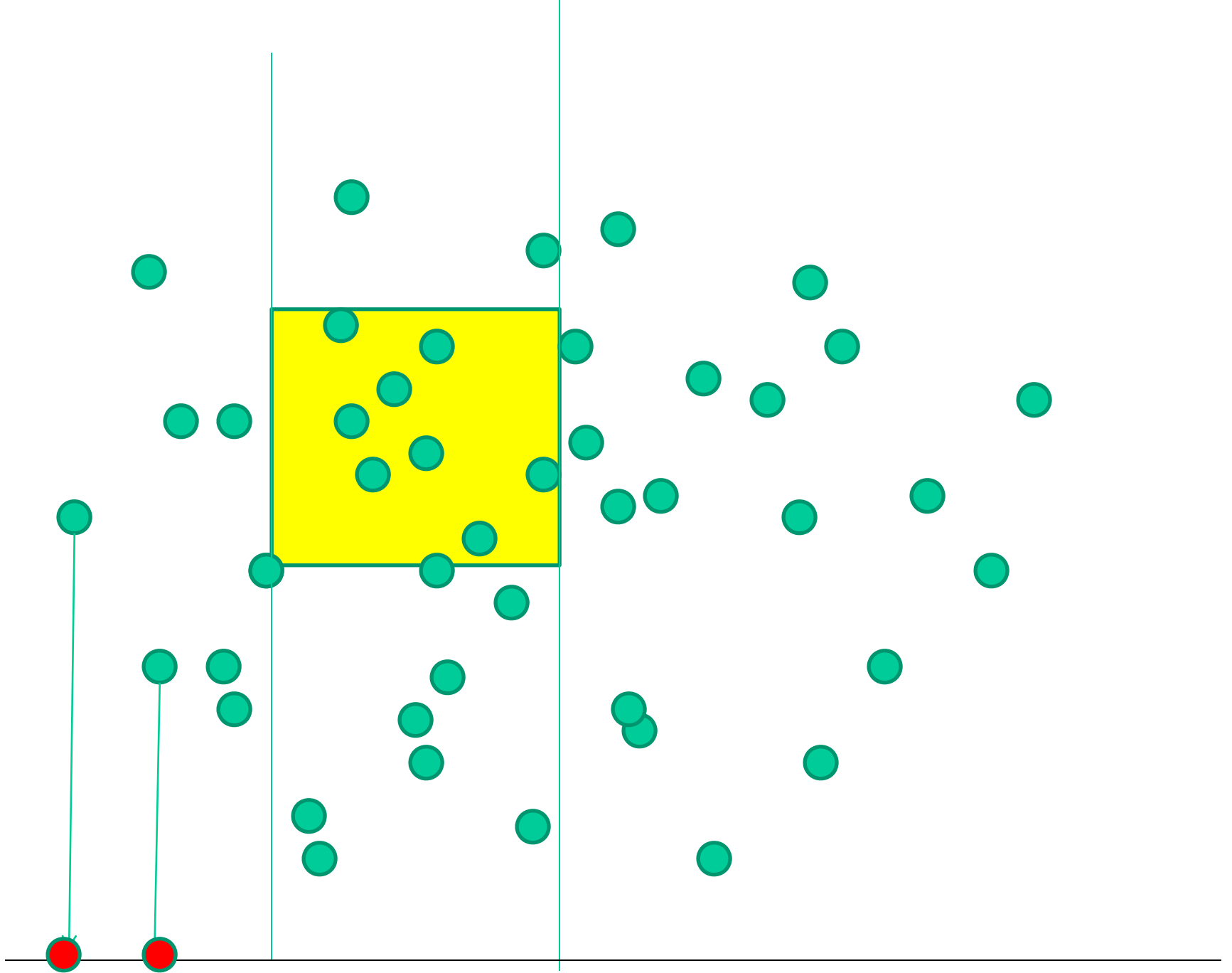
There is a data structure of size  $O(n \log n)$  to answer the counting range query in  $O(\log^2 n)$  time.

- Theorem 5. The counting range query can be done in  $O(\log n)$  time using an  $O(n \log n)$  size data structure.



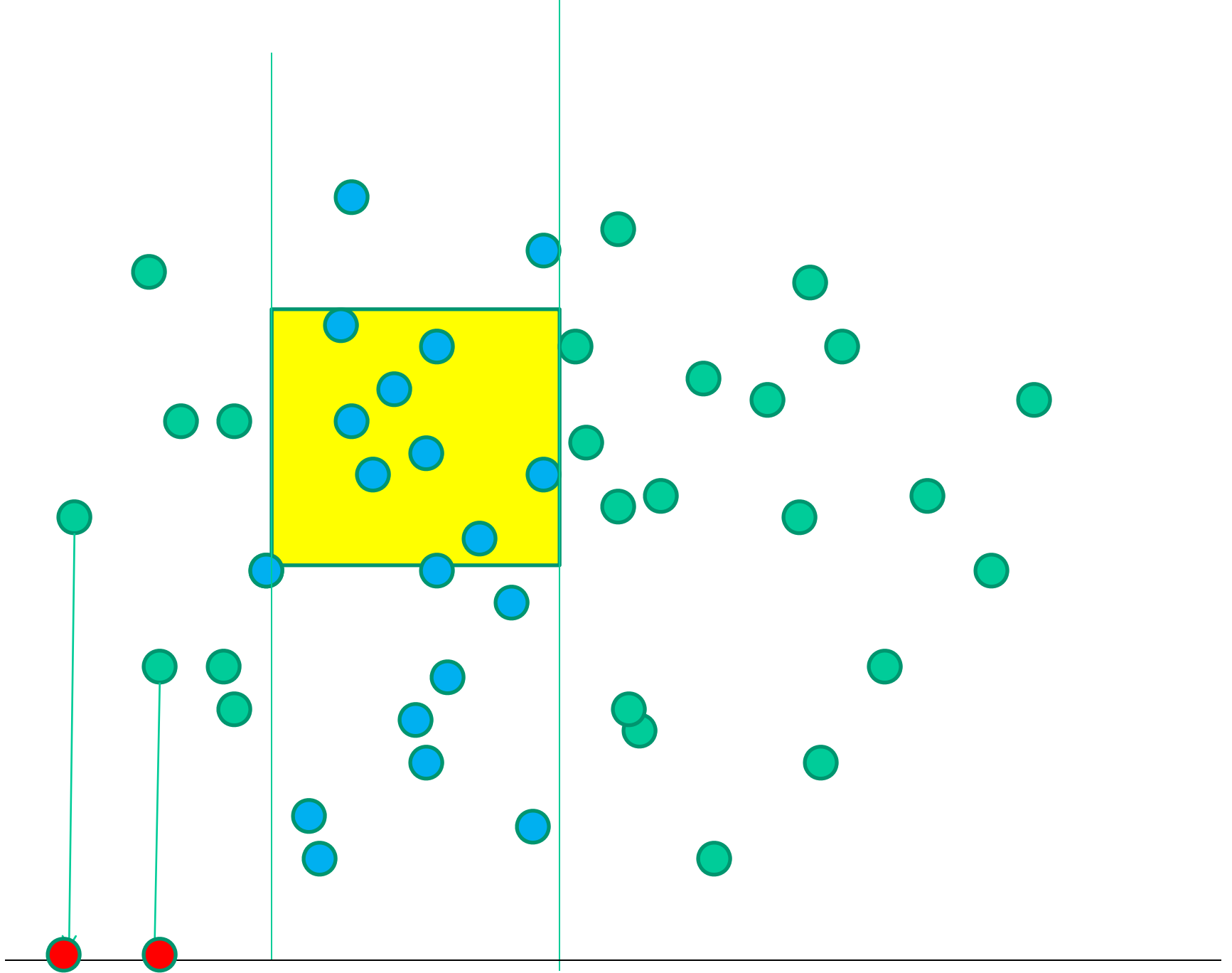


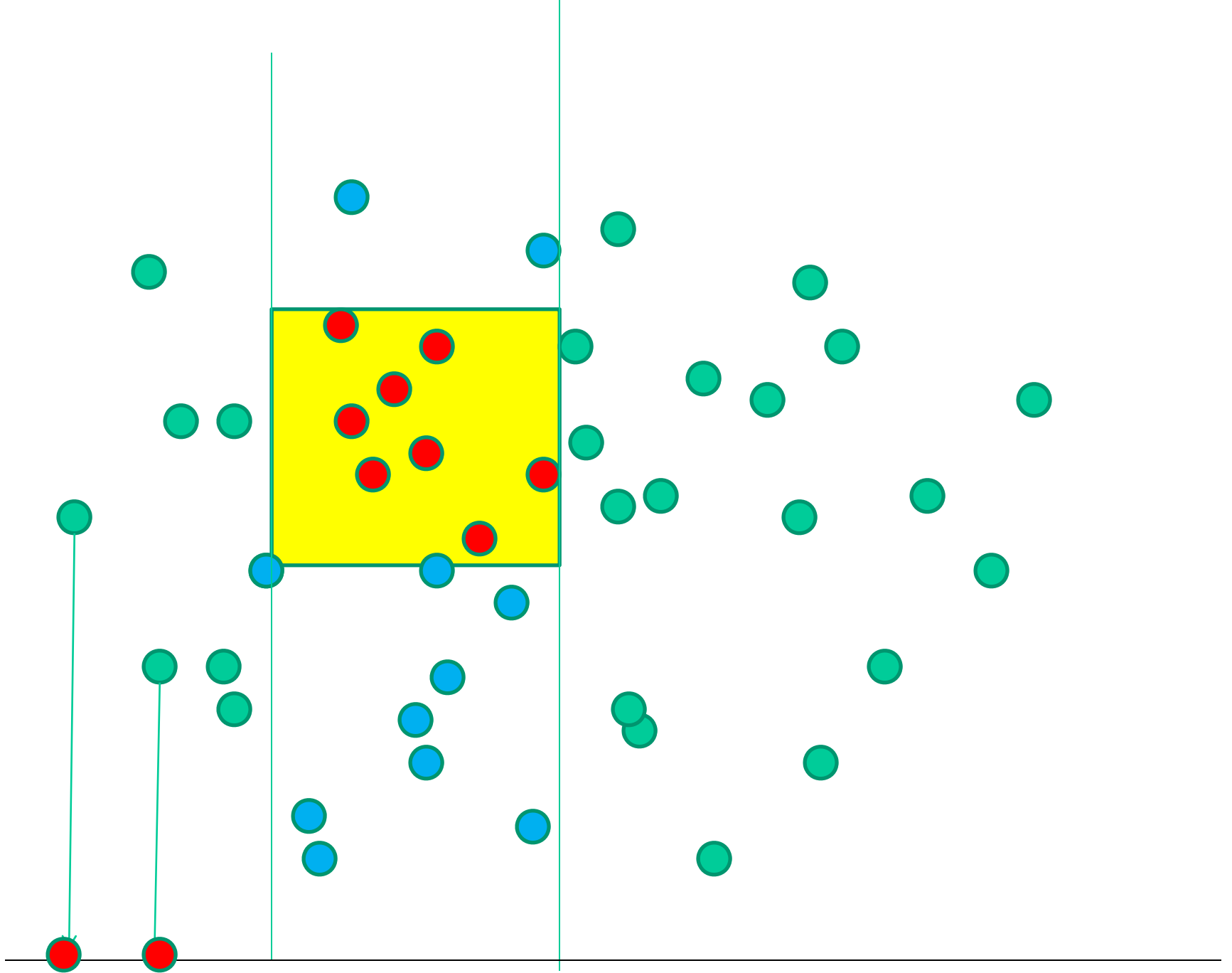




# Idea

- We can find the set of points locating in a given vertical slab
  - Use interval tree on x-values.
- Then, we can find the set of points locating in the horizontal slab
  - Use interval tree of y-values.







3

7

1

6

2

5

4

8

1,2,3,4,5,6,7,8

1,2,3,4

5,6,7,8

1,2

3,4

5,6

7,8

1

2

3

4

5

6

7

8

3,7,1,6,2,5,4,8

3,1,2,4

7,6,5,8

1,2

3,4

6,5

7,8

1

2

3

4

5

6

7

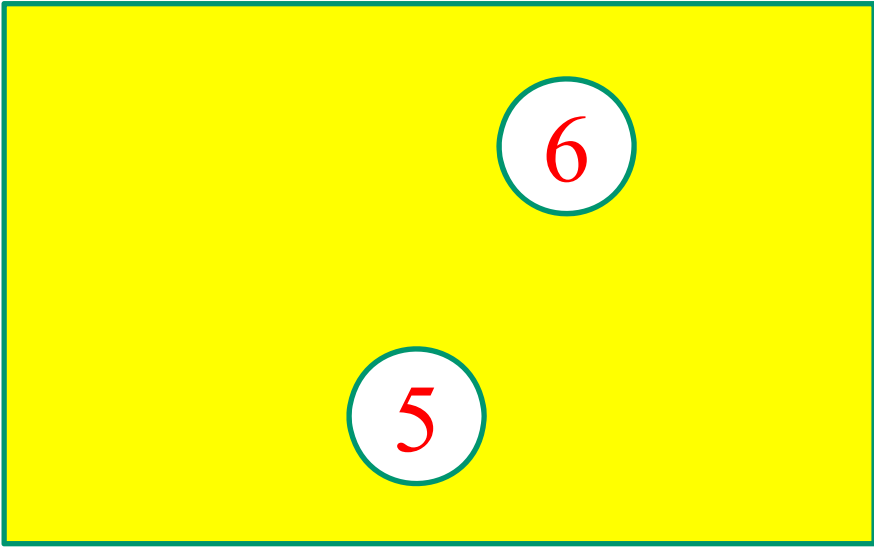
8

1

3

7

2



6

5

4

8

1,2,3,4,5,6,7,8

1,2,3,4

5,6,7,8

1,2

3,4

5,6

7,8

1

2

3

4

5

6

7

8

3,7,1,6,2,5,4,8

3,1,2,4

7,6,5,8

1,2

3,4

6,5

7,8

1

2

3

4

5

6

7

8

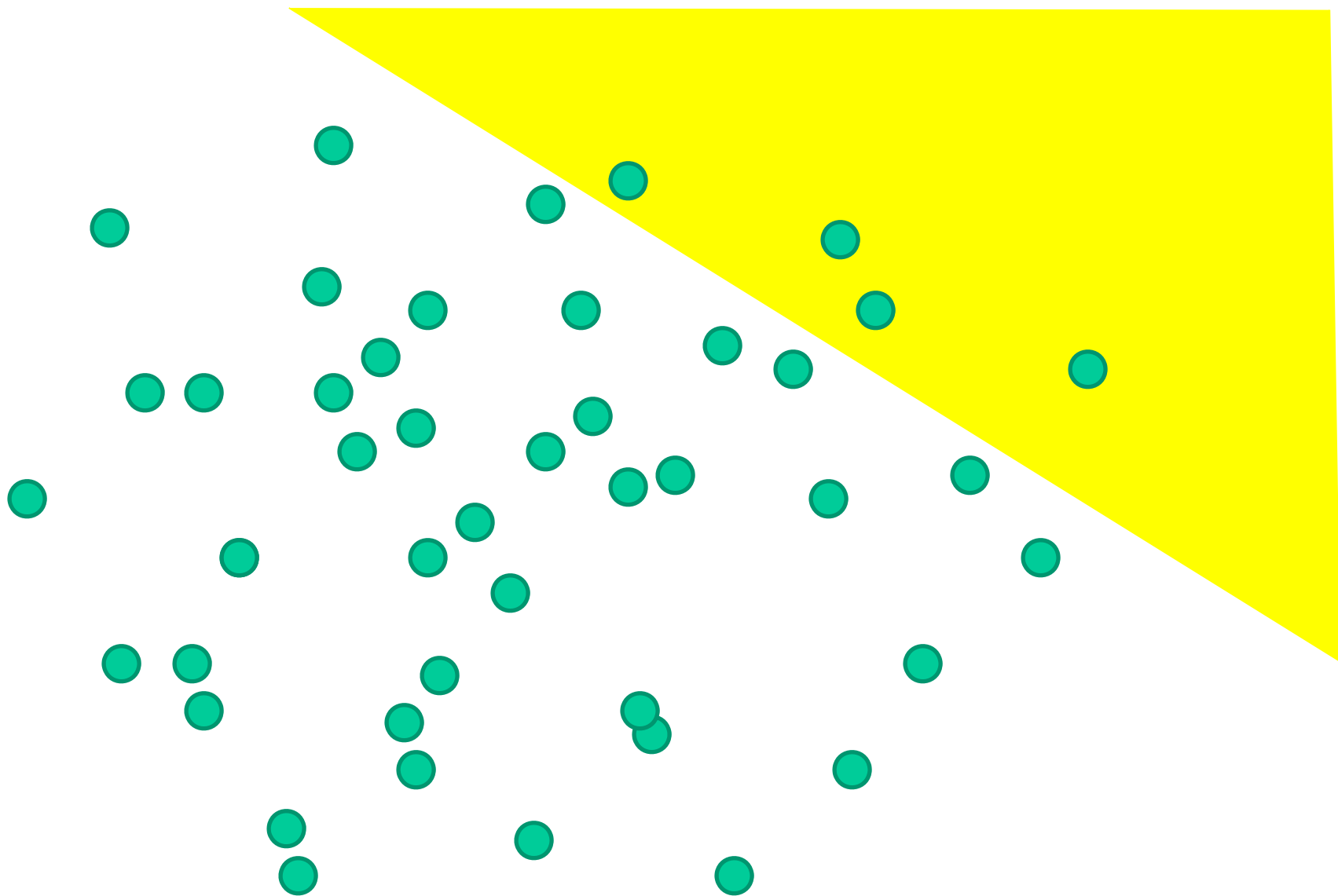
# Analysis

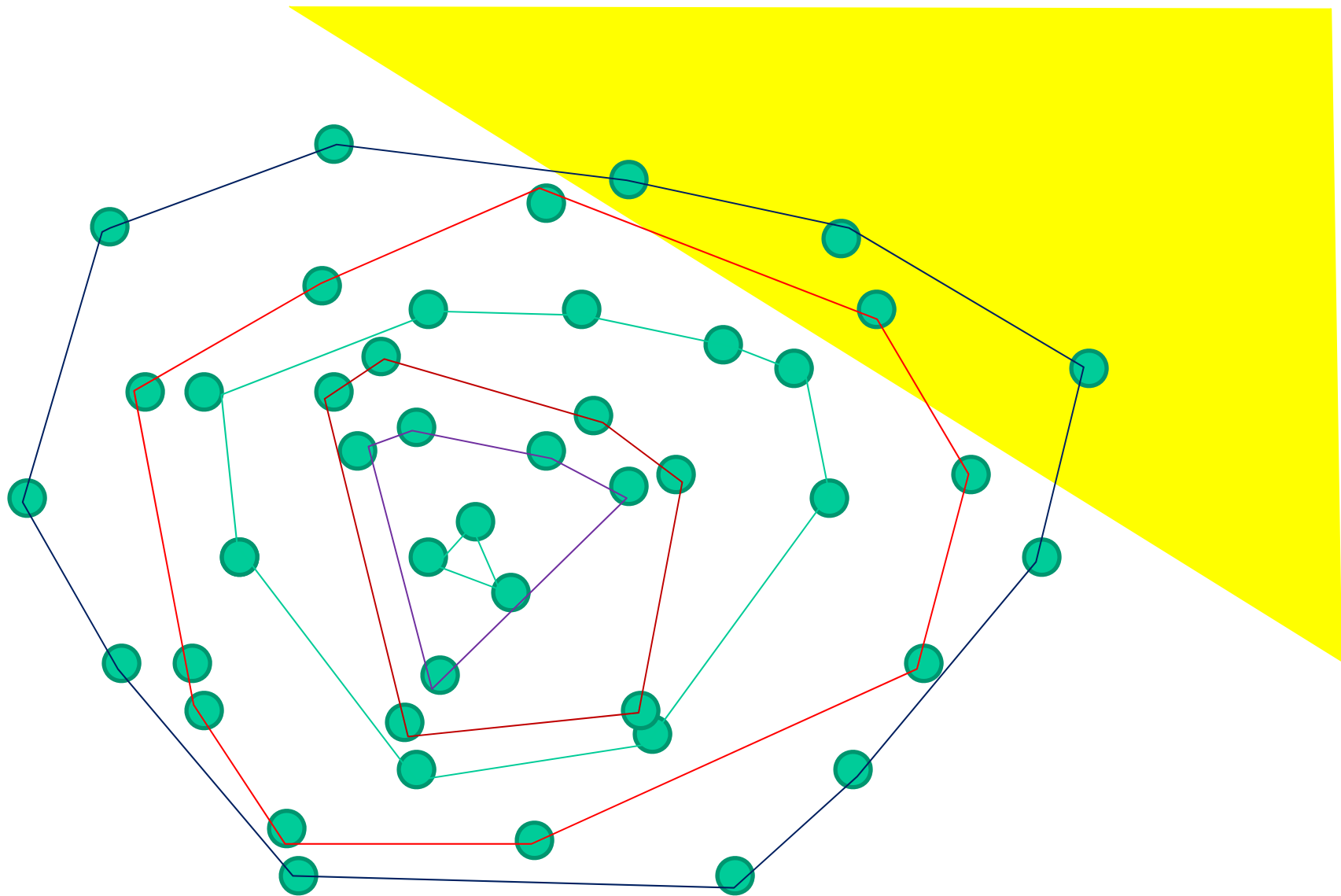
- Size of data structure:  $O(n \log n)$
- Query:  $O(\log^2 n)$
- Improvement to  $O(\log n)$  search
  - Similar list search method
  - Fractional Cascading
- Counting query
- High dimensional analogue

# Halfplane range searching( $d=2$ )

- Given a set  $S$  of  $n$  points in the plane, construct a data structure  $D(S)$ , such that we can do the following query efficiently.
- Halfplane range query: Given a halfplane  $H$ , report the set of points of  $S$  in  $H$  efficiently
- Answer the number of points of  $S$  in  $H$ .







Onion data

# Halfplane reporting query

- Data structure: Onion data structure
  - Chazelle et al 1982
- Query by a halfplane  $H$ 
  - Find all convex chains intersecting  $H$ 
    - Find from the outside
    - Intersecting edges are found
  - Trace on convex chains to find all points in the range
- $O(k \log n)$  time complexity
- Improved to  $O(k + \log n)$

# Halfplane counting query

- The onion method is expensive if  $k$  is large
- The first idea : A.C.Yao-F. Yao (1985)
  - By space subdivision with three lines
- Next idea : H. Edelsbrunner (1986)
  - By Ham-Sandwich Cut
- Next: D. Hausler and E. Welzl (1987)
  - epsilon-net and epsilon sampling
- Next step: E. Welzl (1988)
  - By low stabbing spanning tree
- Final step: J. Matousek (1990)
  - By cutting of arrangement

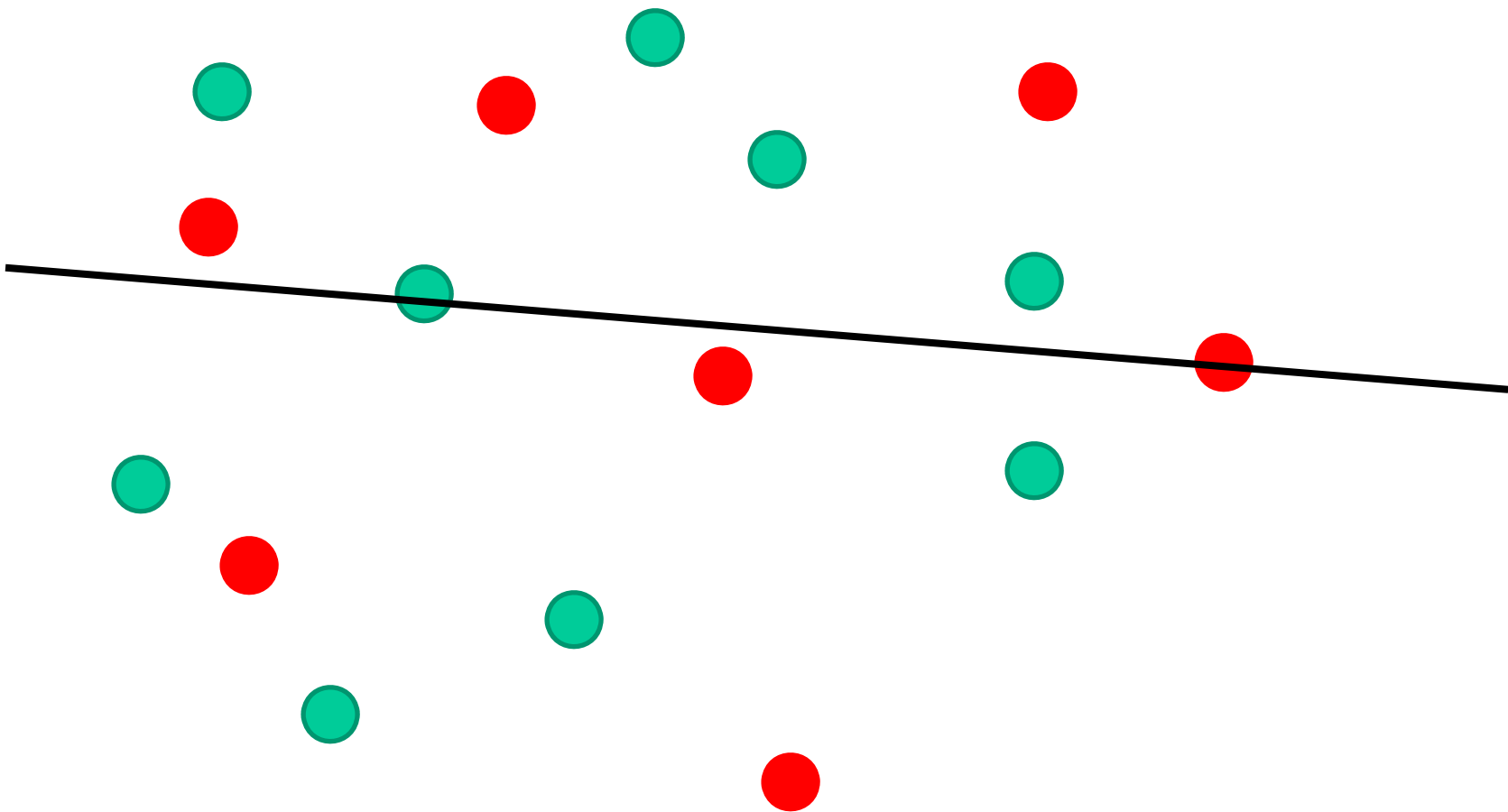
# Ham sandwich cut

- Theorem

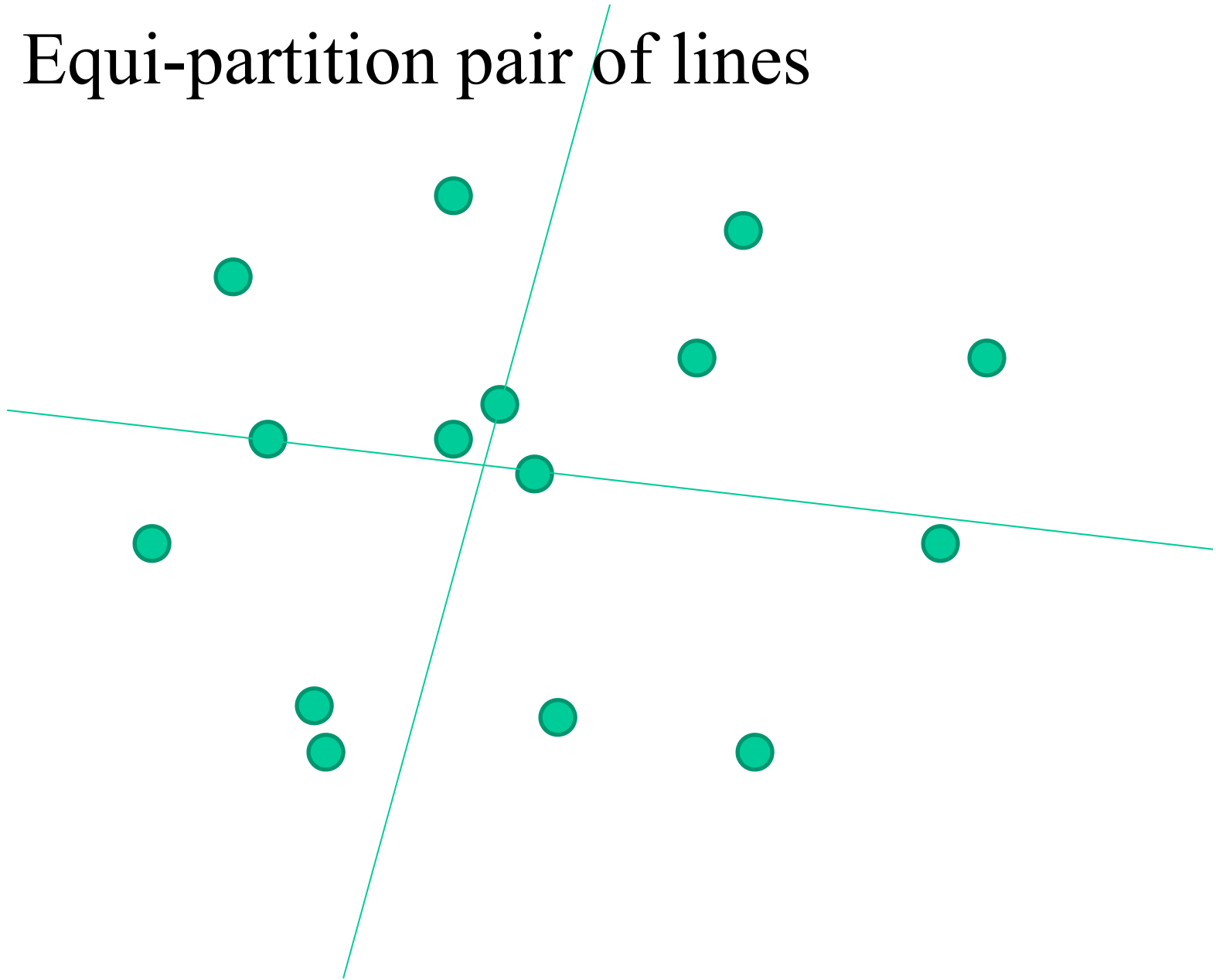
Given  $n$  red points and  $m$  blue points in the plane, there is a line  $L$  such that at most  $n/2$  red points and  $m/2$  blue points lies in each side of  $L$

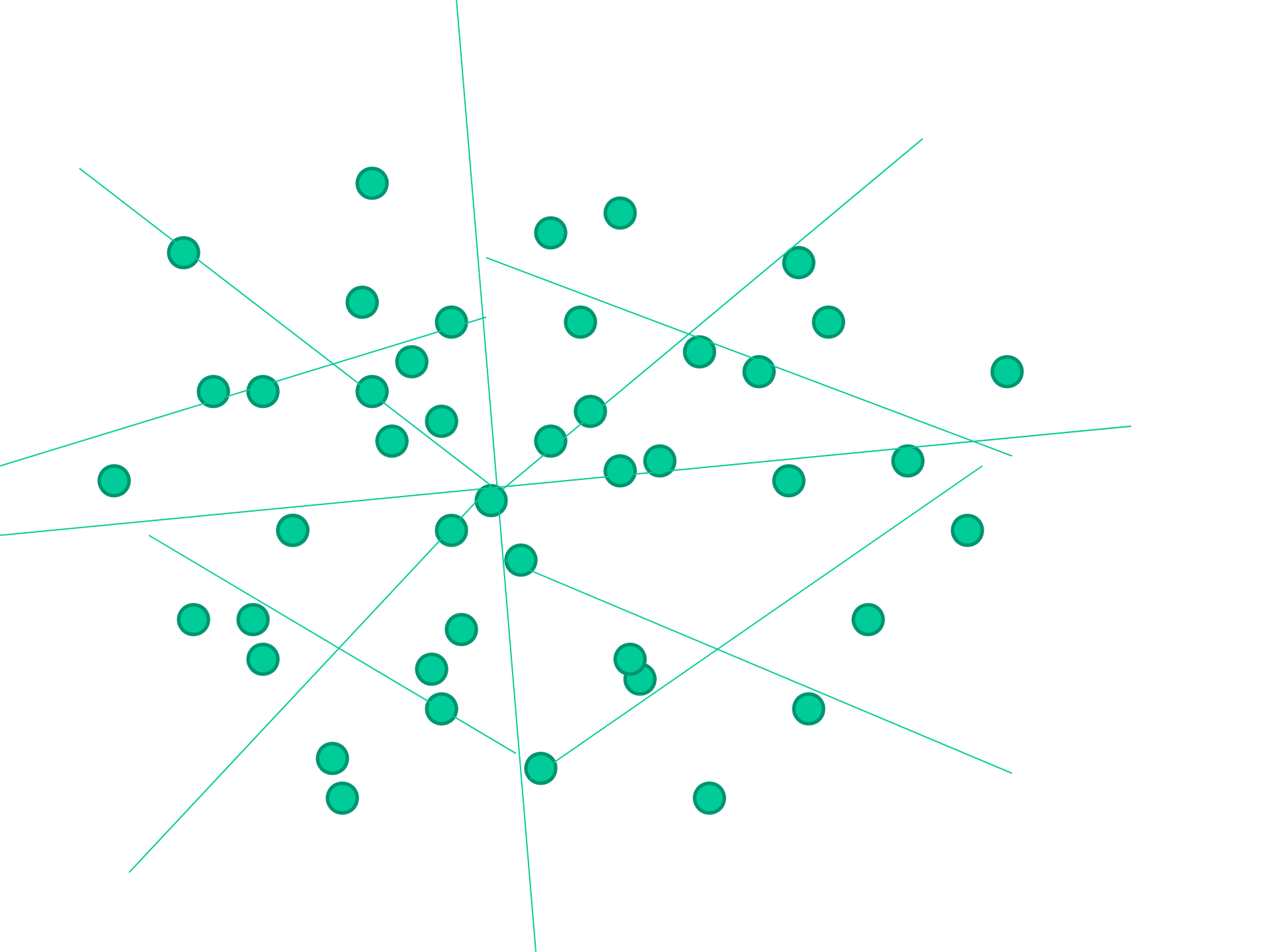
- Obtained from Borsuk-Ulam's theorem

- Any continuous map from circle (sphere) to line (space) has an antipodal pair to map to a same point.
- J. Matousek: Using the Borsuk-Ulam's Theorem



# Equi-partition pair of lines







# How to search?

- Suppose lines  $L$  and  $L'$  partition the space into four cones.
- Then, any line  $M$  intersects at most three cones.
- This gives the following recursion of the search
  - $T(n) = 3 T(n/4) + O(1)$
  - This gives  $T(n) = O(n^{0.7})$